

# Automated SAT-based Analysis of Relational Models and Code

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- ✦ SAT-solving
- ✦ Alloy and the Alloy Analyzer
- ✦ KodKod
- ✦ TACO: Translation of Annotated Code
- ✦ Conclusions and further work

# SAT-Solving

- The SAT problem: given a propositional formula  $A$ , find a satisfying valuation  $v : \text{Vars} \rightarrow \{T, F\}$ .
- First problem to be known as NP-complete.

# SAT-Solving

- A *literal* is a variable  $v$  or its negation (not  $v$ )
- A literal is *pure* if it appears always with the same sign.
- A clause is a disjunction of literals:

$v_1$  or not  $v_2$  or ... or not  $v_k$   $\{v_1, \text{not } v_2, \dots, \text{not } v_k\}$

- A *unit* clause contains a single literal.
- A formula is in *conjunctive normal form* (CNF) if it has the form

$$f = c_1 \text{ and } c_2 \text{ and } \dots \text{ and } c_n$$

where the  $c_i$  are clauses.  $f = \{c_1, c_2, \dots, c_n\}$

# SAT-Solving

The Davis-Putnam-Logemann-Loveland algorithm (1960, 1962):

```
DPLL( $\Phi$ ) =  
  if  $\Phi$  is a consistent set of literals then return  
  true;  
  
  if  $\Phi$  contains an empty clause then  
  return false;  
  
  for every unit clause  $l$  in  $\Phi$   
   $\Phi := \text{unit-propagate}(l, \Phi)$ ;  
  
  for every literal  $l$  that occurs pure in  $\Phi$   
   $\Phi := \text{pure-literal-assign}(l, \Phi)$ ;  
  
   $l := \text{choose-literal}(\Phi)$ ;  
  return DPLL( $\Phi \wedge l$ ) OR DPLL( $\Phi \wedge \text{not}(l)$ );
```

# SAT-Solving: Examples

$$\Phi_1 \wedge \neg \Phi_1 = \{\Phi_1 \wedge \neg \Phi_1\} = \{\} \text{ not } \{v_2, v_3\}$$

```
DPLL( $\Phi$ ) =  
  if  $\Phi$  is a consistent set of literals then return  
    true;  
  
  if  $\Phi$  contains an empty clause then  
    return false;  
  
  for every unit clause  $l$  in  $\Phi$   
     $\Phi := \text{unit-propagate}(l, \Phi)$ ;  
  
  for every literal  $l$  that occurs pure in  $\Phi$   
     $\Phi := \text{pure-literal-assign}(l, \Phi)$ ;  
  
  if there are literals left then  
     $l := \text{choose-literal}(\Phi)$ ;  
    return DPLL( $\Phi \wedge l$ ) OR DPLL( $\Phi \wedge \text{not}(l)$ );
```

# The Alloy Modeling Language (Jackson)

- ✦ Allows to describe data domains, and operations on such domains.
- ✦ The Alloy Analyzer allows to analyze whether properties hold in the models (but within bounded sizes for data domains).

# A Simple Alloy Model

```
sig A {
  one s1: set of A
  fact r: set of A -- a field containing a binary relation
  fact tr: set of A -- only "one" binary identity
  composition of n-ary relations
  property to be verified using the reflexive-transitive closure
}

assert rEqualsItsClosure { Rel.r = A<:*(Rel.r) }
check rEqualsItsClosure for 5
```

gives instructions to the Alloy Analyzer on the sizes of data domains

# Alloy: Relational Semantics

$A$  is a set, unary  $r$  is a  
ternary relation

`sig A { }`      `singleton [Rel]`       $r \text{ in Rel } \times A$

`one sig Rel { r : A -> A }`

`fact reflexive { A<:iden in Rel.r }`

`fact transitive { (Rel.r).(Rel.r) in Rel.r }`

“.” is composition.

`assert rEqualsItsClosure { Rel.r = A<:*(Rel.r) }`

`check rEqualsItsClosure for 5`

$= \{\text{Rel}\}.\{(\text{Rel}, a1, a2): (\text{Rel}, a1, a2) \text{ in } r\}$

$= \{(a1, a2): (\text{Rel}, a1, a2) \text{ in } r\}.$

# The Alloy Analyzer

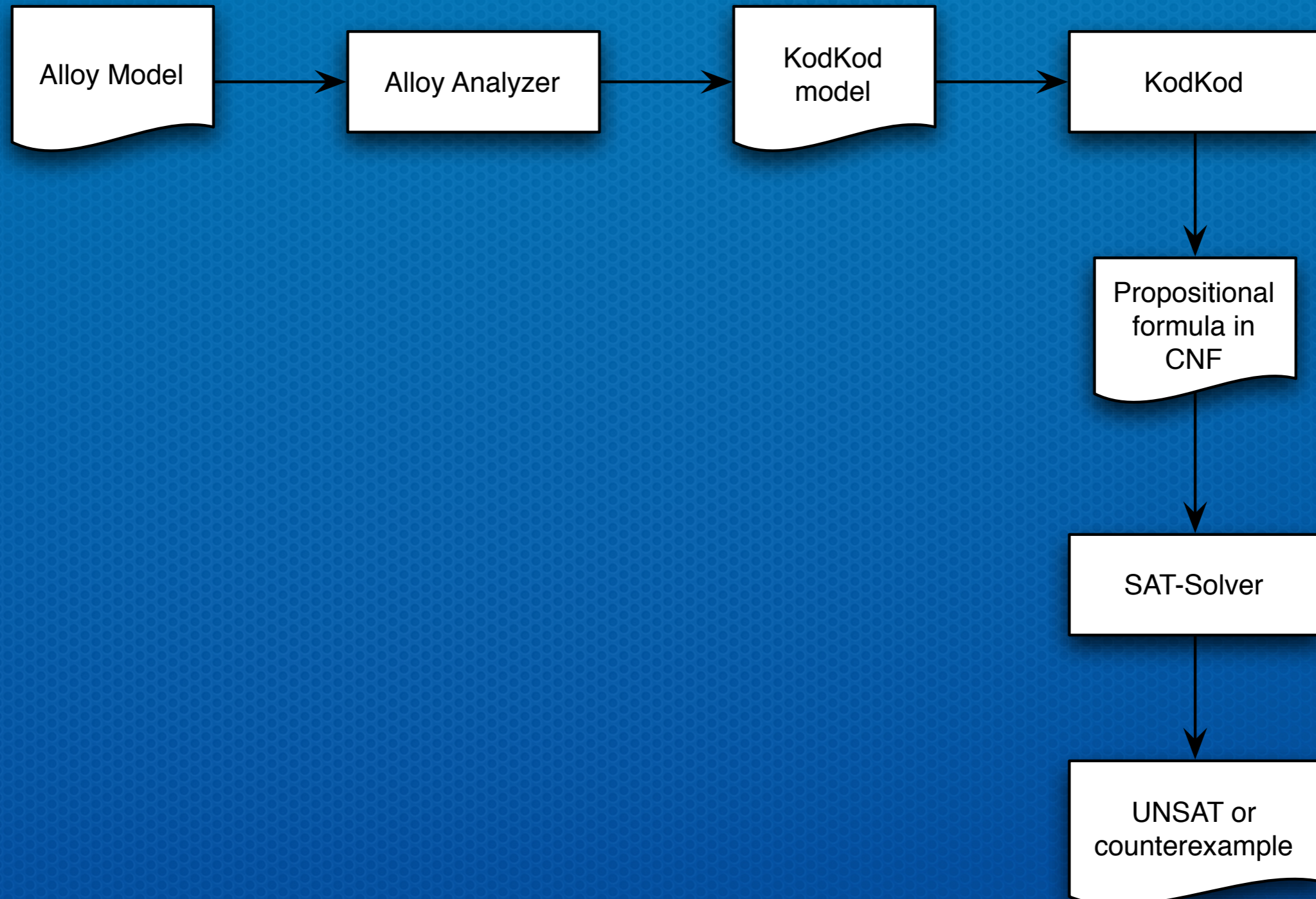
- open rEqualsItsClosure

# The Alloy Analyzer

- ✦ For increasing scopes we get the following analysis times (TO means > 48hours).

8	9	10	11	12	13	14
00:00:04	00:05:22	00:58:58	04:05:41	36:34:13	TO	TO

# The Alloy Analyzer

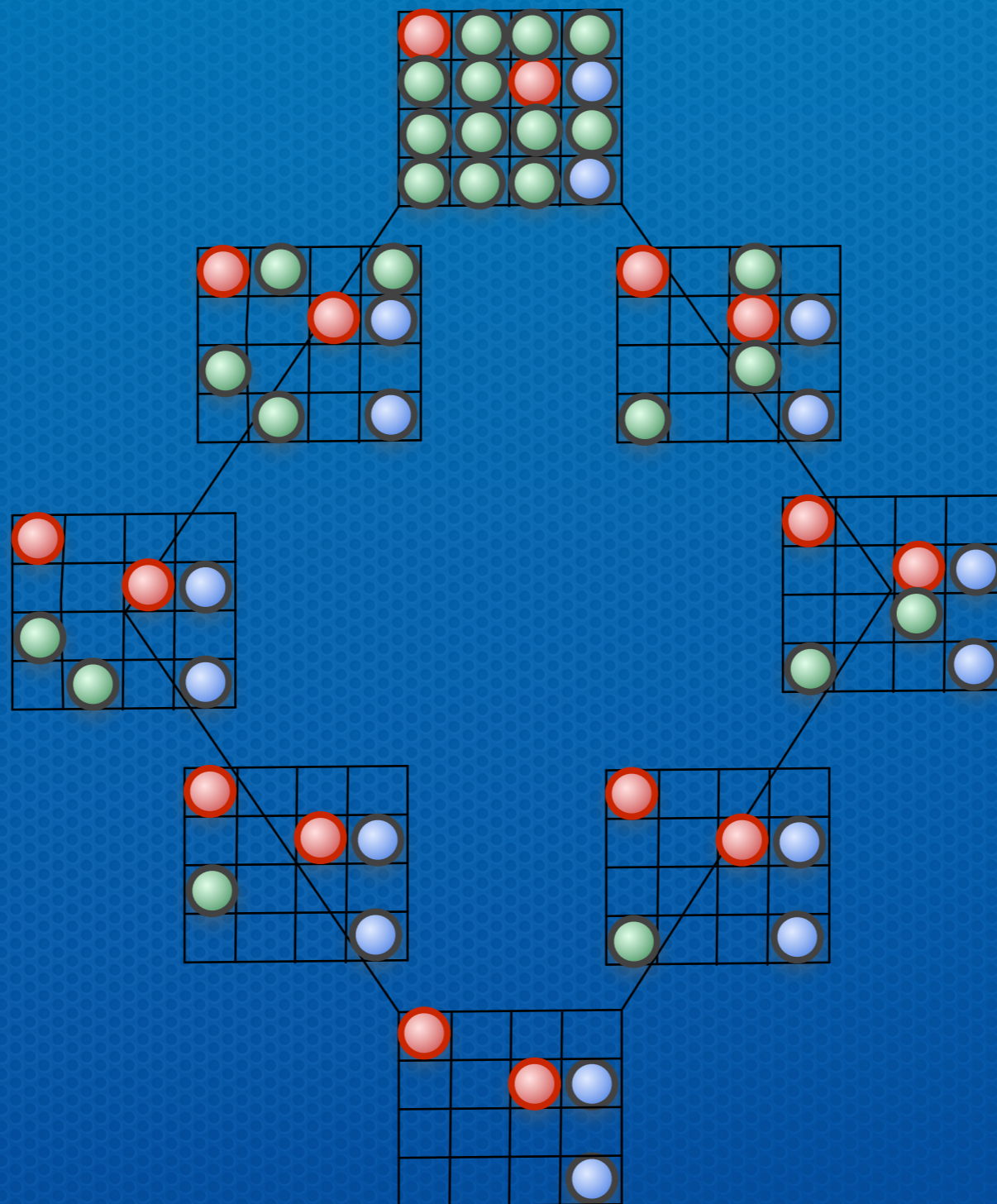


# KodKod (Torlak, Jackson)

- ✦ For each relation symbol  $R$ , there are lower and upper bounds  $l_R$  and  $u_R$ .
- ✦ If a tuple  $t$  in  $l_R$ , then  $t$  must occur in every interpretation for  $R$ .
- ✦ If  $t$  does not occur in  $u_R$ , then  $t$  cannot occur in any interpretation for  $R$ .

# KodKod

Intuitively,



# KodKod: From Relational to Propositional

- Let  $R$  and  $S$  be binary relations on a set  $A$ . Let  $A$ 's scope be 3. Then:

$$R \rightsquigarrow \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ r_{21} & r_{22} & r_{23} \\ r_{31} & r_{32} & r_{33} \end{pmatrix} \quad S \rightsquigarrow \begin{pmatrix} s_{11} & s_{12} & s_{13} \\ s_{21} & s_{22} & s_{23} \\ s_{31} & s_{32} & s_{33} \end{pmatrix}$$

$r_{ij}$  is a propositional variable modeling whether pair  $(i,j)$  is in  $R$ . Similar for  $s_{ij}$ .

# KodKod: From Relational to Propositional

- For transposition (converse), we have:

$$\check{S} \rightsquigarrow \begin{pmatrix} s_{11} & s_{21} & s_{31} \\ s_{12} & s_{22} & s_{32} \\ s_{13} & s_{23} & s_{33} \end{pmatrix}$$

Relational terms are mapped to matrices of propositional formulas

- For join (union), we have:

$$R + \check{S} \rightsquigarrow \begin{pmatrix} r_{11} \vee s_{11} & r_{12} \vee s_{21} & r_{13} \vee s_{31} \\ r_{21} \vee s_{12} & r_{22} \vee s_{22} & r_{23} \vee s_{32} \\ r_{31} \vee s_{13} & r_{32} \vee s_{23} & r_{33} \vee s_{33} \end{pmatrix}$$

# KodKod: From Relational to Propositional

- For equalities between terms:

$$R + \check{S} = T$$

$$\vdots$$

$$\left( \begin{array}{cc} r_{12} \vee s_{21} & r_{13} \vee s_{31} \\ r_{22} \vee s_{22} & r_{23} \vee s_{32} \\ r_{31} \vee s_{11} & r_{32} \vee s_{23} \\ r_{33} \vee s_{33} \end{array} \right) = \left( \begin{array}{ccc} t_{11} & t_{12} & t_{13} \\ t_{21} & t_{22} & t_{23} \\ t_{31} & t_{32} & t_{33} \end{array} \right)$$

$$\vdots$$

$$(r_{11} \vee s_{11} \Leftrightarrow t_{11}) \wedge (r_{12} \vee s_{21} \Leftrightarrow t_{12}) \wedge (r_{13} \vee s_{31} \Leftrightarrow t_{13}) \wedge \dots$$

It is  
extended to  
connectives  
and  
quantifiers

# DynAlloy (Frias et al.)

- ✦ Is an extension of Alloy to model behavior.
- ✦ Semantics inspired on Dynamic logic.
- ✦ Allows to define atomic and composite actions.

# DynAlloy: Atomic Actions

```
action Increment[x: Int] {  
  pre { gt[x,0] }  
  post { x' = add[x,1] }  
}
```

Precondition  
to be satisfied by input

Postcondition.  
Primed variables denote values  
in the final state

# DynAlloy: Complex actions

- ✦  $A1 + A2$  : Nondeterministic choice
- ✦  $A1 ; A2$  : sequential composition
- ✦  $\alpha ?$  : test action ( $\alpha$  is an Alloy formula)
- ✦  $*A$  : reflexive transitive closure

# DynAlloy: Analyzability

- We can analyze partial correctness assertions within domain scopes.
- We bound the number of iterations of the  $*$ .

```
assertCorrectness IncrementTwiceAdds2[x : Int] {  
  pre = { gt[x,0] }  
  program = {  
    Increment[x];  
    Increment[x]  
  }  
  post = { x' = add[x,2] }  
}
```

# Automated Analysis of Java Code

- ✦ Map the Java class hierarchy to the Alloy signatures hierarchy.
- ✦ Map Java atomic sentences to atomic actions.
- ✦ Map Java programs to DynAlloy.

# Java to DynAlloy: Atomic

```
act NewC[o : C]
  pre = { true }
  post = { o' !in ObjectsC and o' in ObjectsC' }
```

```
act Setf[o : C, v : C', f : C -> C']
  pre = { o in ObjectsC }
  post = { f' = f ++ (o -> v) }
```

```
act VarAssign[v1, v2 : C] (abbreviated v1 := v2)
  pre = { true }
  post = { v1' = v2 }
```

# Java to DynAlloy: Code

`stmt1 ; stmt2`  $\mapsto$  `stmt1; stmt2,`

`if (pred) stmt1 else stmt2`  $\mapsto$  `(pred?; stmt1) +  
((!pred)?; stmt2)`

`while (pred) {stmt}`  $\mapsto$  `*(pred?; stmt); (!pred)?,`

# Java to DynAlloy: Example

Ensures: property to be established by the method.

“result = true iff x is the value of a node in the list”

```
public class LNode extends Object {
    LNode next;
    int key;
}

public class List extends Object {
    /*@
    @ invariant (\forall LNode n;
    @   \reach(this.head, LNode, next).has(n);
    @   !\reach(n.next, LNode, next).has(n));
    @*/
    LNode head;
}
```

```
/*@
@ ensures (\exists LNode n;
@   \reach(this.head, LNode, next).has(n) &&
@   n.val==x) <==> \result == true;
@*/
boolean find(int x) {
    LNode current;
    boolean output;
    current = this.head;
    output = false;
    while (output==false && current!=null) {
        if (current.val == x) {
            output = true; }
        current = current.next;
    }
    return output;
}
```

# Class Hierarchy and Code

```
boolean find(int x) {  
    LNode current;  
    sig Object {}  
    one sig null {}  
    sig List extends Object {}  
    sig LNode extends Object {}  
    sig Throwable extends Object {}  
    sig Exception extends Throwable {}  
    sig RuntimeException extends Exception {}  
    one sig NullPointerException extends RuntimeException {}  
}  
return output;
```

```
program find[  
    this_L:List, result:Boolean, x:Int,  
    head:List->one(LNode+null),  
    next:LNode->one(LNode+null),  
    val:LNode->one Int]{  
    var [current:LNode, output:Boolean]  
    current := this_L.head;  
    output := False[];  
    while (output=False[] && current!=null) {  
        if (current.val = x) {  
            output := True[]  
        }  
        current := current.next;  
    }  
    result := output  
}
```

# Java to DynAlloy: Checking Correctness

```
assertCorrectness find[this_L:List, result:Boolean,  
  x:Int,  
  head : List -> one (LNode + null),  
  next : LNode -> one (LNode + null),  
  key : LNode -> one Int ]{  
pre { List_Inv[this_L, head, next] }  
program { find[this_L, result, x, head, next, key] }  
post {ensures_find[this_L,head,next,key,x,result']  
      && List_Inv[this_L, head, next] }  
}
```

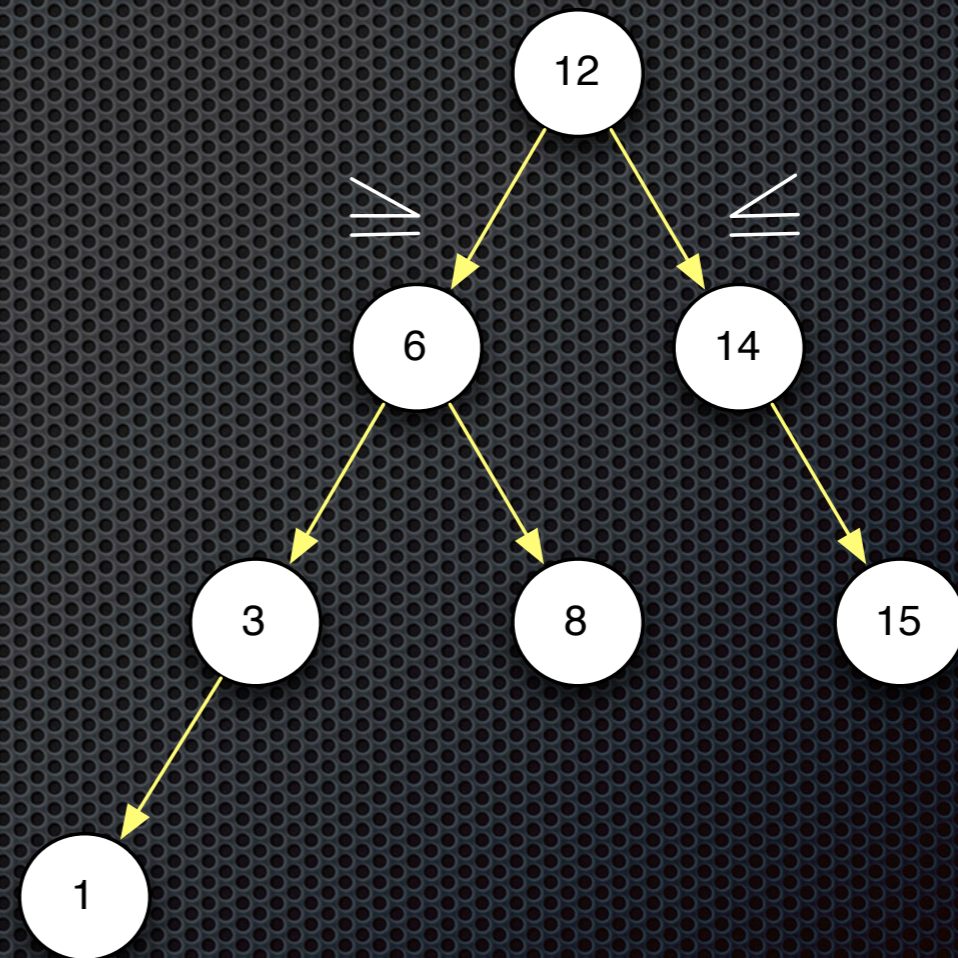
check find for 5

# TACO: Efficient Analysis of Java Code

- ✦ TACO: Translation of Annotated COde.
- ✦ Uses an efficient technique for reducing KodKod upper bounds.
- ✦ Analysis speeds up by several orders of magnitude.
- ✦ Experiments show that it improves over state-of-the-art tools based on model checking or SMT-solving.

# A Sample Problem

Generating an instance of AVL-tree.



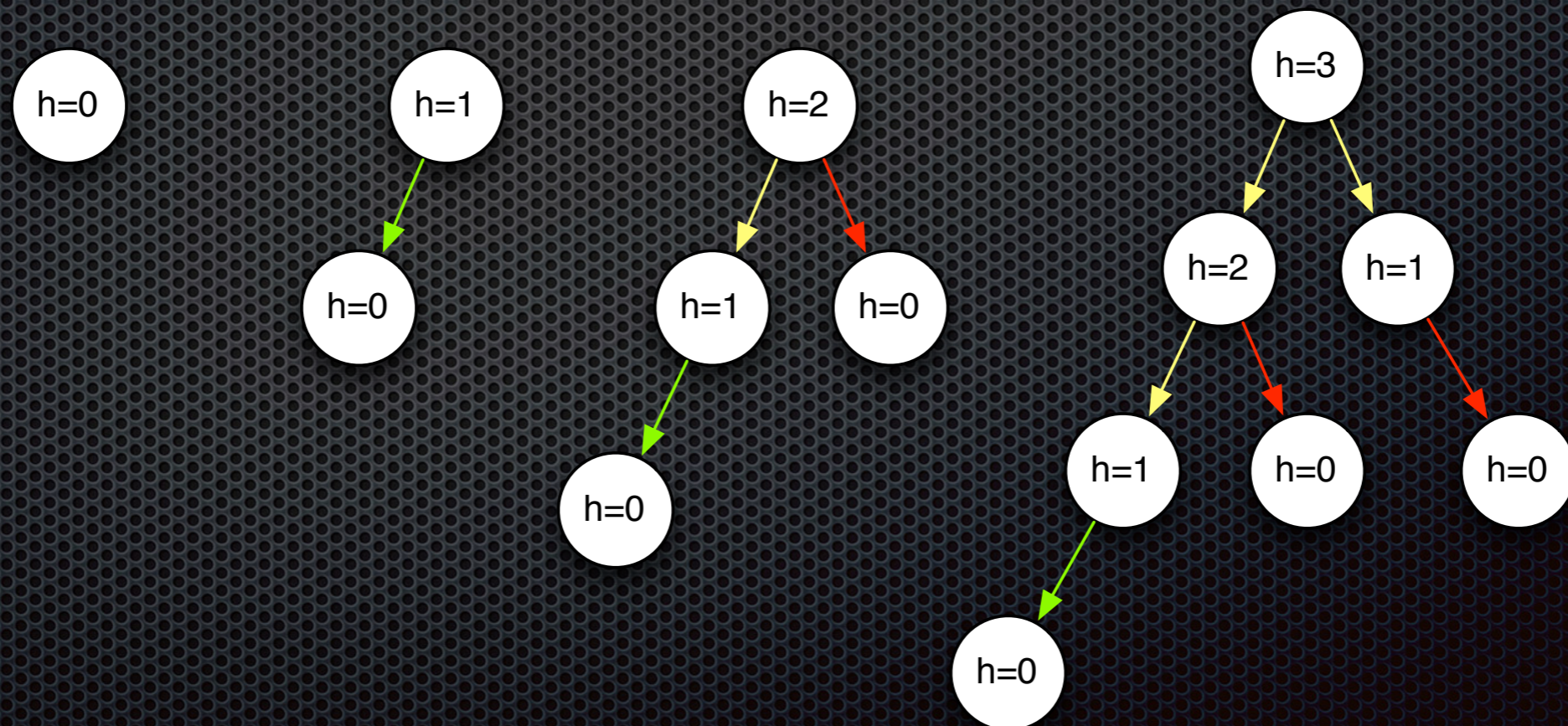
1. Binary tree,
2. Ordered,
3. Balanced:  $|h(\text{left}(n)) - h(\text{right}(n))| \leq 1$

# Technique: Fully Automated Bound Refinement

- To find an instance the SAT-solver attempts to find (using strategies for pruning the state space) a tree `this`, and functions for fields `root`, `h`, `left` and `right` such that the invariant is satisfied.

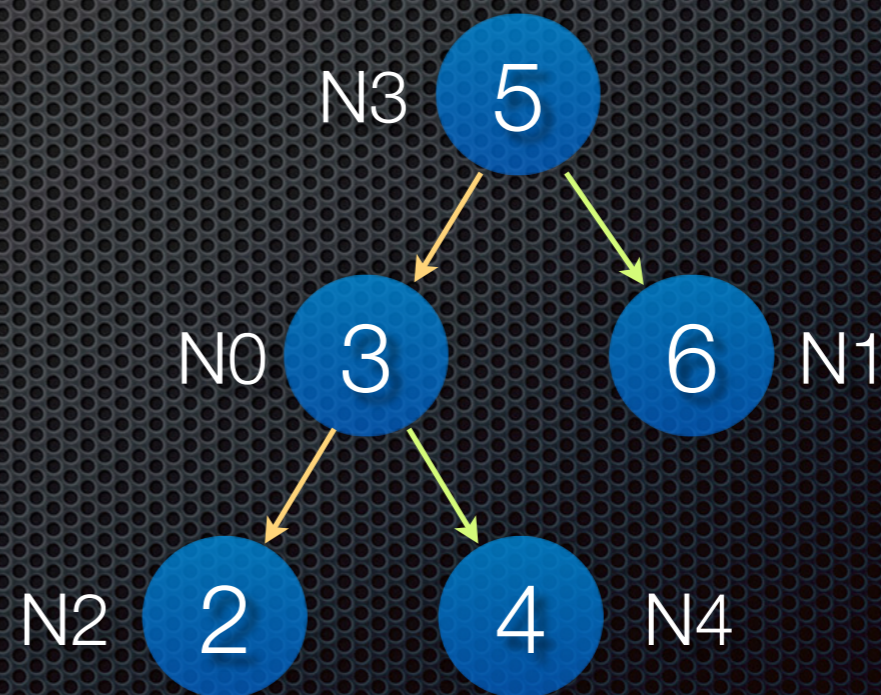
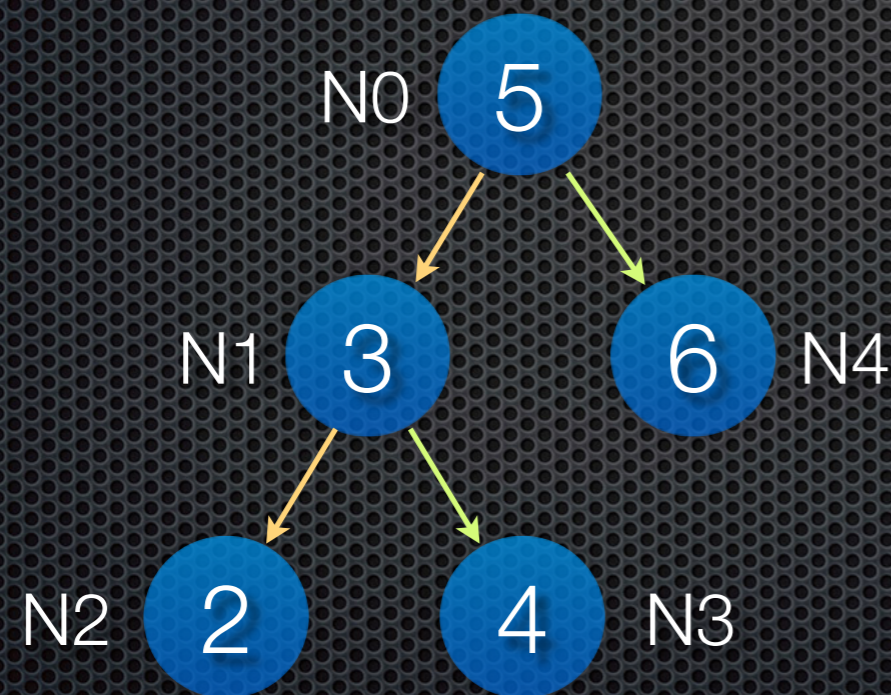
# For AVL trees...

- Regarding field **h**, notice that all leaves have  $h = 0$ . Besides, since these are balanced trees, for up to 7 nodes no node satisfies  $h(n)$  greater than 3.



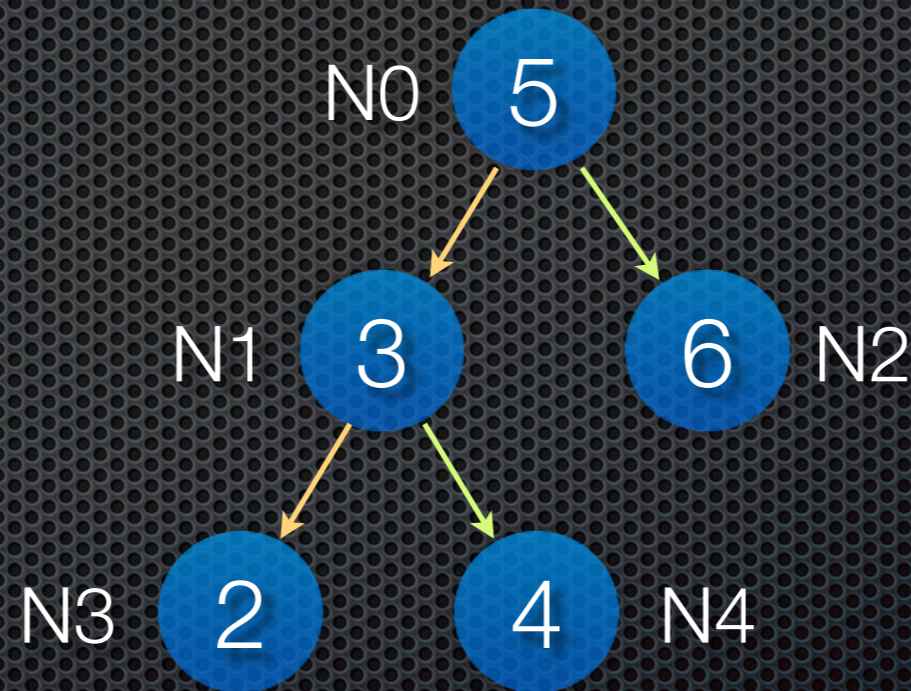
# For AVL trees...

- Since nodes are objects, a node can hold different values (at different times). For instance:

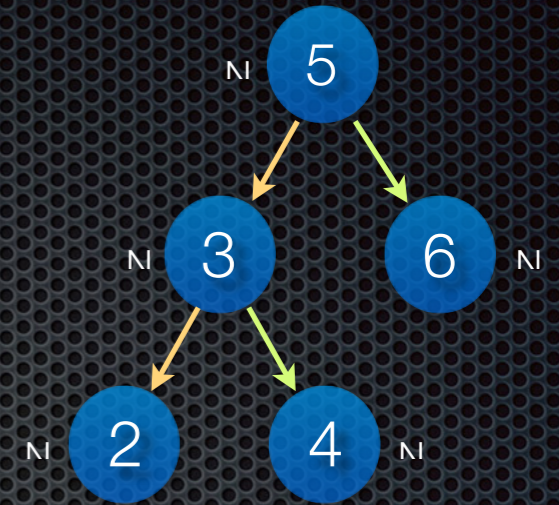


# For AVL trees...

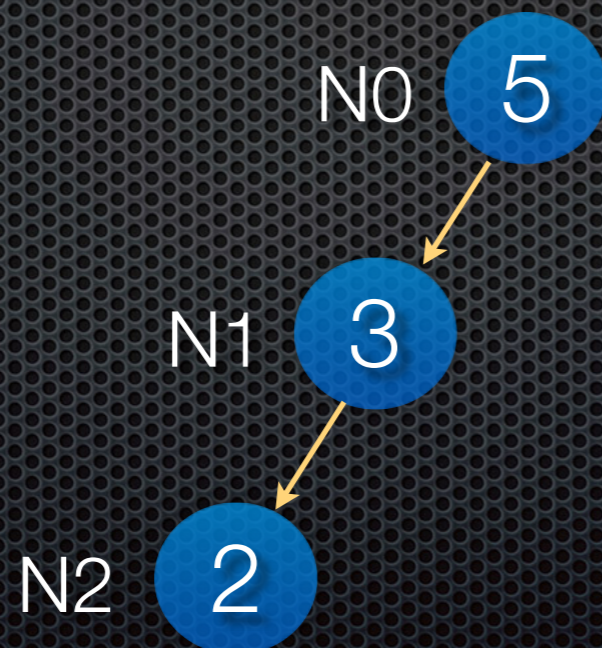
- But if we **force** nodes to be traversed in BFS order...



# For AVL trees...



- Is it possible for N0 to point to a node that is neither N1 nor N2?
- Is it possible for N2 to be pointed to by a node other than N0?



Is not AVL!

# Therefore, there are infeasible values...

- ✦ For instance, for a tree with up to 7 nodes,  $h(n) \leq 3$  for all node  $n$ .
- ✦  $\text{Left}(N_0)$  is either  $N_1$  or null (but not  $N_2, N_3, \dots$ )
- ✦  $\text{Right}(N_0)$  is  $N_1, N_2$  or null (but not  $N_3, N_4, \dots$ )
- ✦  $\text{Right}(N_i) \neq N_2$  for  $i \neq 0$ .

# Therefore, there are infeasible values...

- ✦ These values correspond to tuples in fields, and therefore, correspond to propositional variables in the KodKod translation.
- ✦ If we can remove these infeasible variables, the SAT-solver has fewer assignments to try.

# Refining bounds reduces to:

- ✦ Forcing nodes to be allocated using a BFS traversal.
- ✦ Establishing the infeasible variables for each field.
- ✦ Doing all this in a **fully automatic manner**.

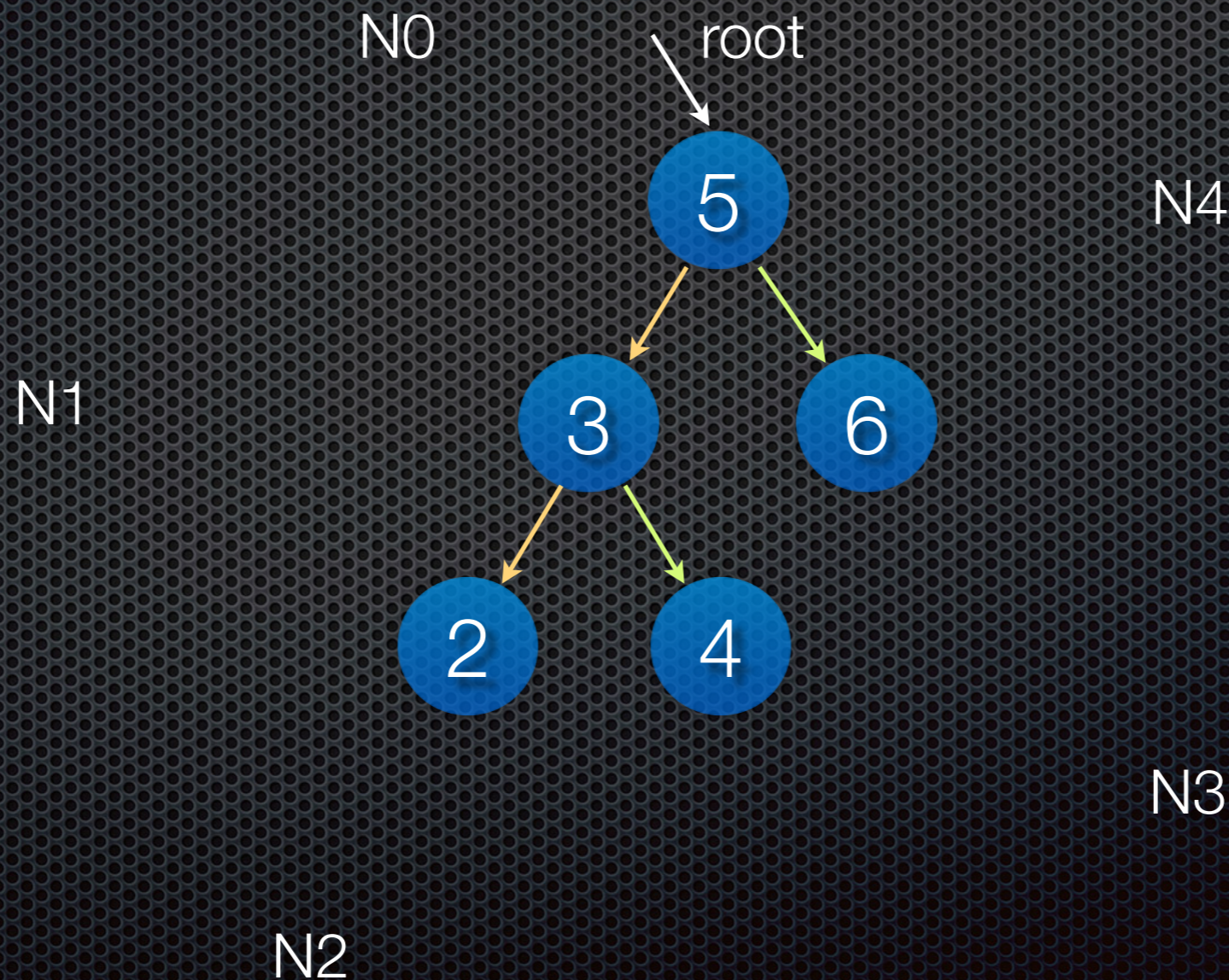
# Hints:

- ✦ Instrument the relational model with new formulas forcing nodes to be allocated using a BFS ordering.
- ✦ Check feasibility for each pair in a class field.

# Instrumenting the model

Rule2: Two nodes with the same parent are labeled from left to right.

Applying once again Rule 2,



# Testing feasibility

Naive approach: use a cluster to analyze all pair in fields in parallel.

N0.left = N0,  
N0.left = N1,  
...  
N0.h = 0,  
N0.h = 1,  
...

For 20 nodes, there are  
2120 analyses to be performed.

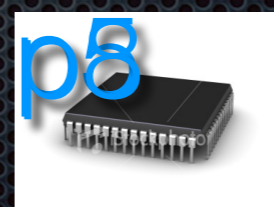
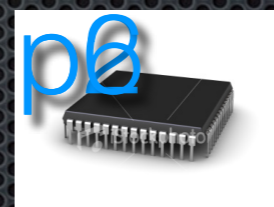
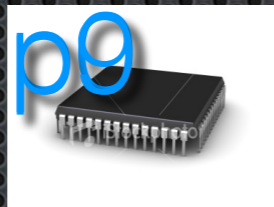
Problem...  
generating an AVL tree with  
20 nodes does not  
finish.  
No refined  
bounds yet!

# An Effective Approach

p11 p10 p9 p8 p7 p6 p5 p4 p3 p2 p1 p0

Bound

p0	p1	p2
p3	p4	p5
p6	p7	p8
p9	p10	p11



SATs

UNSATs

TIMEOUTS

# Demo 2: Instances from refined bounds.

open generateAVL10Nodes.als (aprox. 1 minute)

open instGenerateAVL15Nodes.als

# Code Analysis: Experimental Results

We compare with:

- ✦ JForge (MIT)
- ✦ Java Pathfinder (NASA)
- ✦ KIASAN (Kansas State University)
- ✦ ESC/Java2 (University College Dublin)
- ✦ Jahob (ETH - Zurich)

# Code Analysis: Experimental Results

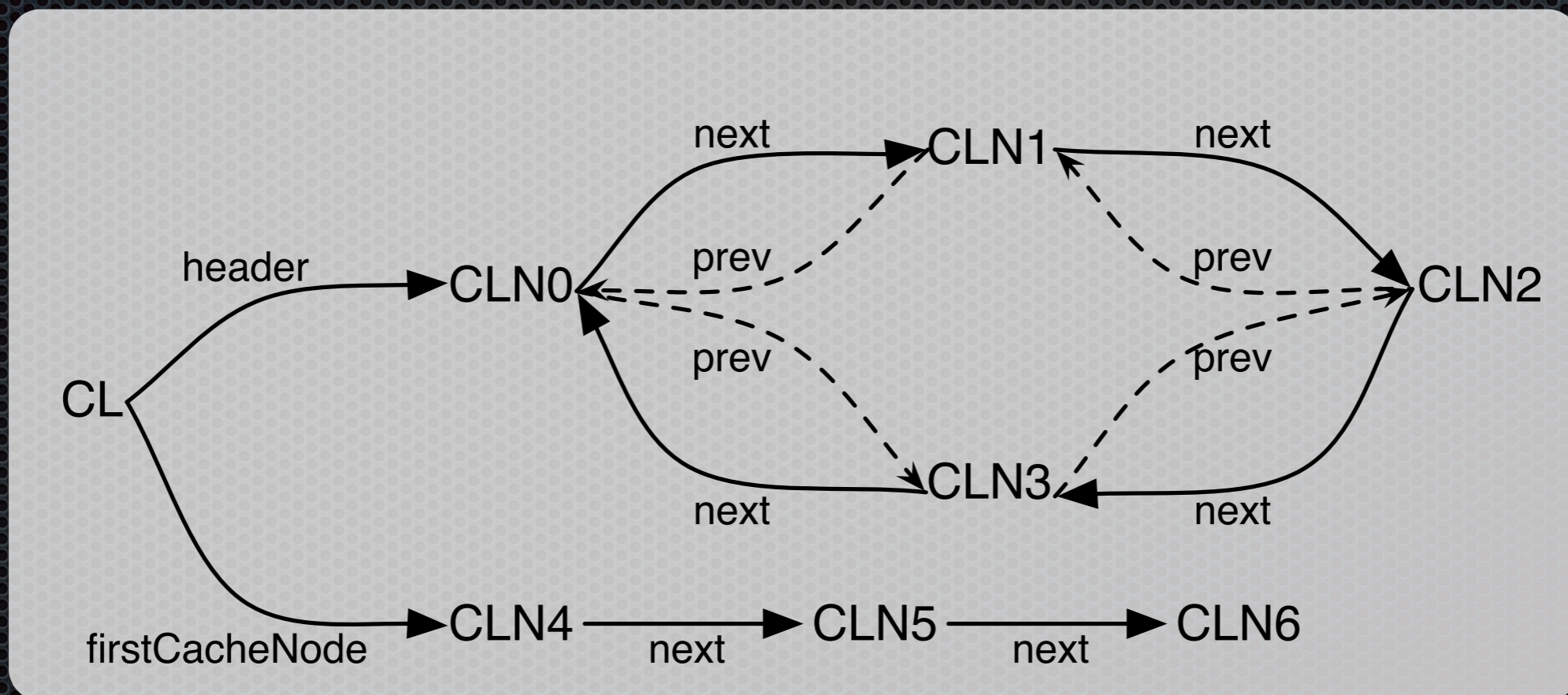
			5	7	10	12	15	17
LList	Cont	NI	00:03	00:05	00:08	00:11	00:13	00:22
		JF	00:01	02:00	TO	TO	TO	TO
		I	00:03	00:04	00:05	00:06	00:07	00:09
	Ins	NI	00:04	00:09	01:14	00:33	04:26	01:25
		JF	00:02	04:56	TO	TO	TO	TO
		I	00:04	00:05	00:07	00:08	00:13	00:26
	Rem	NI	00:05	00:27	TO	TO	TO	TO
		JF	00:04	21:51	TO	TO	TO	TO
		I	00:04	00:06	00:11	00:12	00:17	00:33
AList	Cont	NI	00:05	00:11	00:29	00:38	00:42	01:20
		JF	00:02	05:01	TO	TO	TO	TO
		I	00:04	00:06	00:16	00:22	00:27	00:58
	Ins	NI	00:04	00:05	01:02	26:22	TO	TO
		JF	00:03	11:52	TO	TO	TO	TO
		I	00:04	00:05	00:07	00:08	00:12	00:16
	Rem	NI	00:06	00:14	11:25	05:47:39	TO	TO
		JF	00:18	01:13:27	TO	TO	TO	TO
		I	00:05	00:06	00:17	00:31	01:08	03:13
TreeSet	Find	NI	02:13	04:36:49	TO	TO	TO	TO
		JF	00:42	01:57:49	TO	TO	TO	TO
		I	00:04	00:10	01:56	12:43	58:54	05:05:06
	Ins	NI	21:38	TO	TO	TO	TO	TO
		JF	OofM	OofM	OofM	OofM	OofM	OofM
		I	00:43	08:44	TO	TO	TO	TO

# Code Analysis: Experimental Results

AVL	Find	NI	00:14	27:06	TO	TO	TO	TO
		JF	00:26	03:10:10	TO	TO	TO	TO
		I	00:03	00:06	00:36	01:41	08:20	33:06
	FMax	NI	00:02	00:04	46:12	TO	TO	TO
		JF	00:06	49:49	TO	TO	TO	TO
		I	00:01	00:01	00:03	00:04	00:09	00:13
	Ins	NI	01:20	05:35:51	TO	TO	TO	TO
		JF	OofM	OofM	OofM	OofM	OofM	OofM
		I	00:07	00:34	04:47	21:53	02:53:57	TO
BHeap	Min	NI	00:03	00:41	TO	TO	TO	TO
		JF	00:22	01:23:07	TO	TO	TO	TO
		I	00:02	00:04	00:11	00:20	02:29	00:07
	DecK	NI	00:30	38:58	TO	TO	TO	TO
		JF	01:48	TO	TO	TO	TO	TO
		I	00:10	00:59	24:05	02:42:30	TO	00:26
	Ins	NI	01:55	51:22	TO	TO	TO	TO
		JF	01:13:47	TO	TO	TO	TO	TO
		I	00:16	01:05	10:44	21:31	01:20:09	51:55

# Finding a Nontrivial Bug

- Cache Lists: include a cache where removed nodes are stored so that they are not garbage collected.



# Experimental Results

```
public Object remove(int index) {  
    Node node = getNode(index, false);  
    Object oldValue = node.getValue();  
    super.removeNode(node);  
    if (cacheSize >= maximumCacheSize){  
        return;  
    }  
    Node nextCacheNode = firstCacheNode;  
    node.previous = null;  
    node.next = nextCacheNode;  
    firstCacheNode = node;  
    return oldValue;  
}
```

```
public Object remove(int index) {  
    Node node = getNode(index, false);  
    Object oldValue = node.getValue();  
    super.removeNode(node);  
    if (cacheSize > maximumCacheSize){  
        return;  
    }  
    Node nextCacheNode = firstCacheNode;  
    node.previous = null;  
    node.next = nextCacheNode;  
    firstCacheNode = node;  
    return oldValue;  
}
```

LU	JForge	ESC/Java2	JPF	Kiasan	Jahob	TACO
4	OofM(227)	OofM(206)	TO	OofM(4)	03:03:19	03:52 + 03:56
6	TO	OofM(207)	TO	OofM(4)	05:05:29	03:52 + 31:14
8	OofM(287)	OofM(213)	TO	OofM(4)	07:39:01	03:52 + 33:23
10	05:40:22	OofM(215)	TO	OofM(4)	TO	03:52 + 00:11
12	06:53:04	OofM(219)	TO	OofM(4)	TO	03:52 + 03:30
15	24:08	OofM(219)	TO	OofM(4)	TO	03:52 + 15:00
20	TO	OofM(218)	TO	OofM(4)	TO	03:52 + 00:06

✿ Thanks!

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(Joint work with Juan Galeotti and Nicolas Rosner)

